

# Linear Algebra

[KOMS120301] - 2023/2024

## 14.1 - Intuition behind eigenvectors

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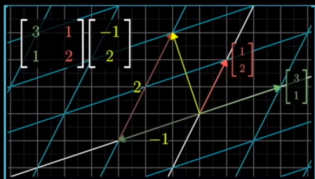
Week 14 (December 2023)

# Learning objectives

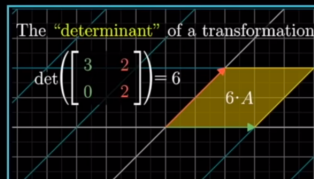
- Recap what we learned in the previous weeks;
- Get an intuitive understanding of the concept;
- Relate it to the concept of linear transformation.

# What we have learned

## Linear transformations



## Determinants



## Linear systems

$$\begin{cases} 2x+5y+3z = -3 \\ 4x+0y+8z = 0 \\ 1x+3y+0z = 2 \end{cases} \rightarrow \begin{bmatrix} 2 & 5 & 3 \\ 4 & 0 & 8 \\ 1 & 3 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -3 \\ 0 \\ 2 \end{bmatrix}$$

## Change of basis

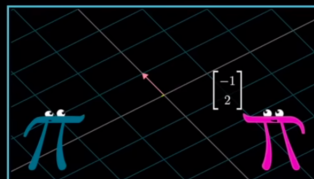
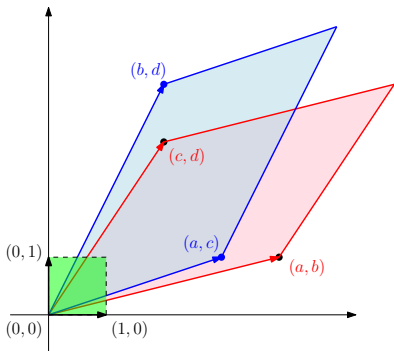


Figure: Prerequisites (source: Youtube of 3Blue1Brown)

# Geometric interpretation of **determinant** (*from Week 5*)



Matrix  $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$  can be viewed as an “arrangement” of:

- row vectors:  
 $\begin{bmatrix} a & b \end{bmatrix}$  and  $\begin{bmatrix} c & d \end{bmatrix}$
- or, column vectors:  
 $\begin{bmatrix} a \\ c \end{bmatrix}$  and  $\begin{bmatrix} b \\ d \end{bmatrix}$

The matrix defines the so-called *linear transformation* of the unit square (in green) formed by the *basis vectors*  $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$  and  $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ , with respect to:

- the **row vectors**, shown by the **red** parallelogram; or
- the **column vectors**, shown by the **blue** parallelogram

Both parallelograms have the **same area**. Prove it!

Vectors that “stay in their position” after transformation

# Transformation of basis vectors (1)

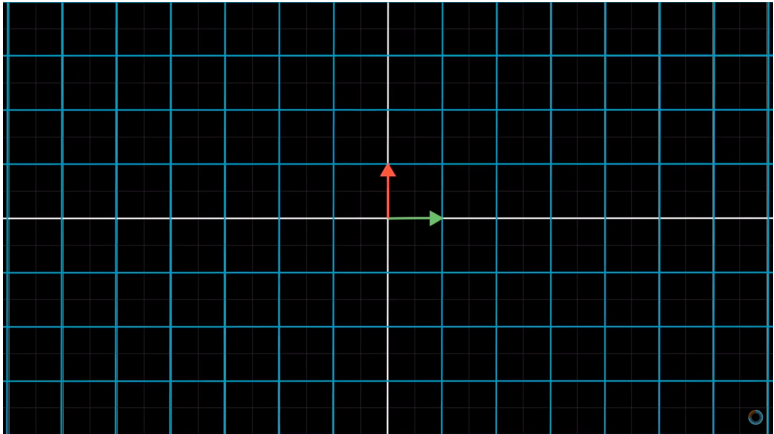


Figure: Two basis vectors in standard system (source: Youtube of 3Blue1Brown)

## Transformation of basis vectors (2)

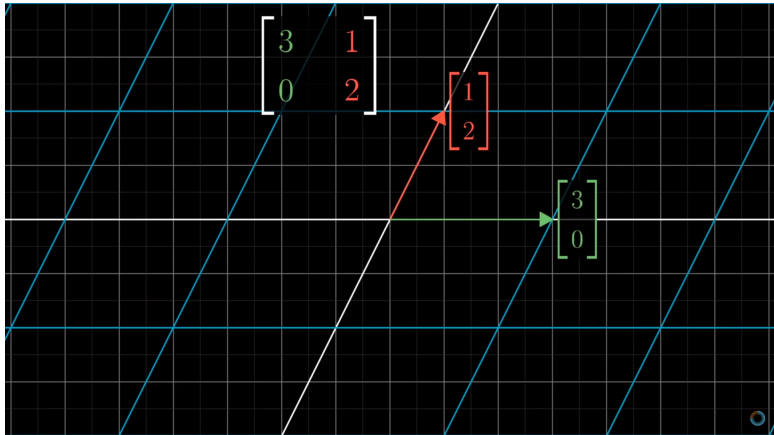


Figure: Result of transformation of the basis vectors remain in its "position" (source: Youtube of 3Blue1Brown)

## Transformation of basis vectors (3)

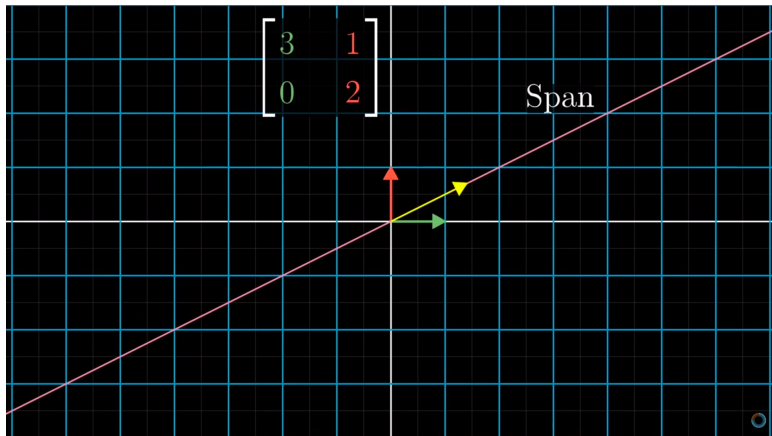


Figure: A (yellow) vector and its span (source: Youtube of 3Blue1Brown)



## Transformation of basis vectors (4)

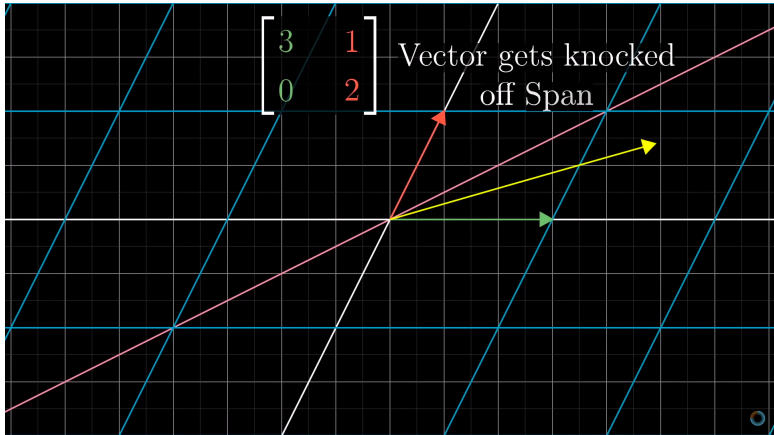


Figure: The yellow vector does not stay in its position (*source: Youtube of 3Blue1Brown*)

## Transformation of basis vectors (5)

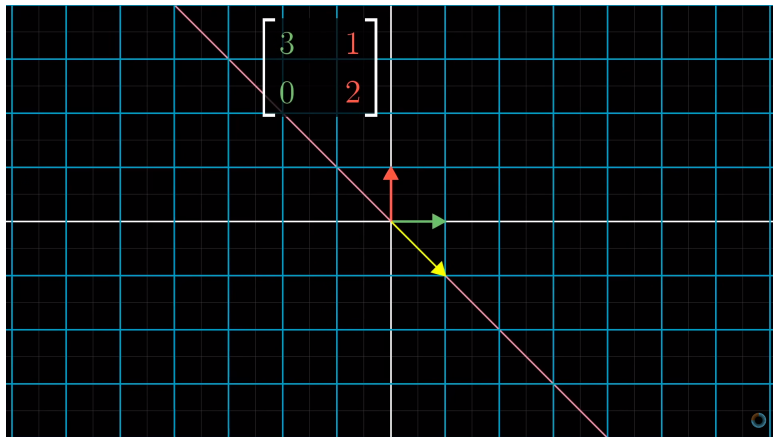


Figure: Another yellow vector (source: Youtube of 3Blue1Brown)

## Transformation of basis vectors (6)

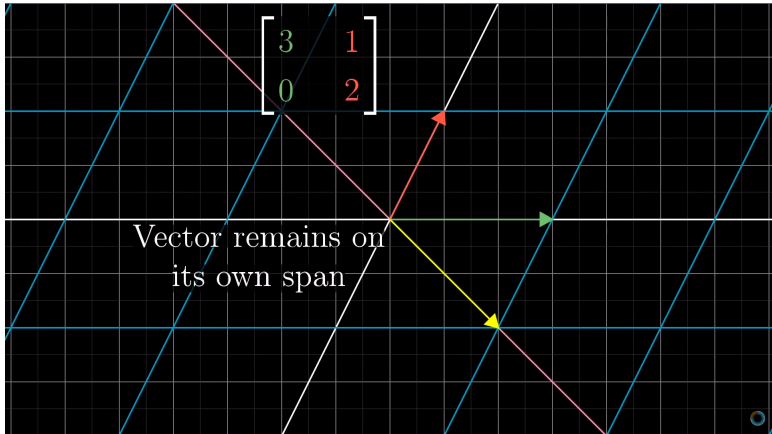


Figure: The vector remains in its position after transformation (*source: Youtube of 3Blue1Brown*)

## Transformation of basis vectors (7)

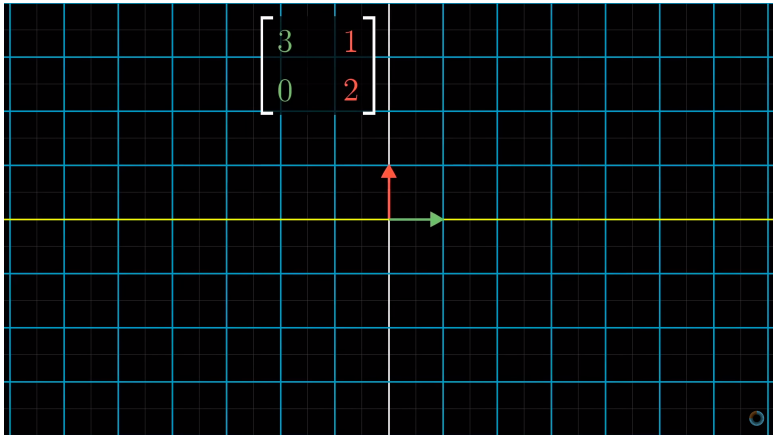
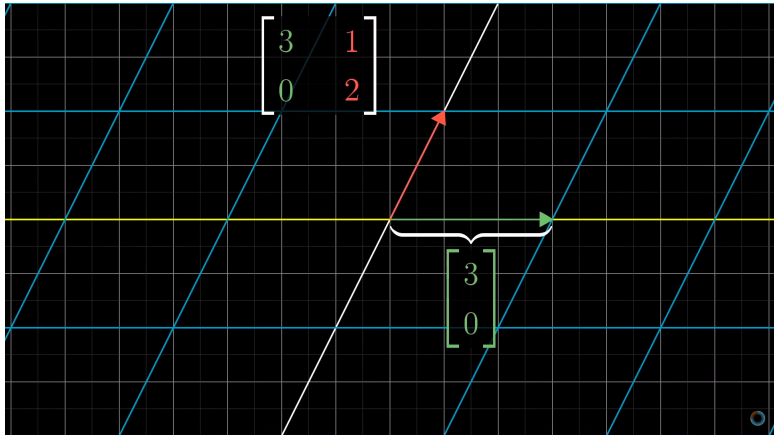


Figure: What happens to the green basis vector and its span? (*source: Youtube of 3Blue1Brown*)

## Transformation of basis vectors (8)



**Figure:** The green vector remains in its position, and multiplies by 3  
(source: Youtube of 3Blue1Brown)

## Transformation of basis vectors (9)

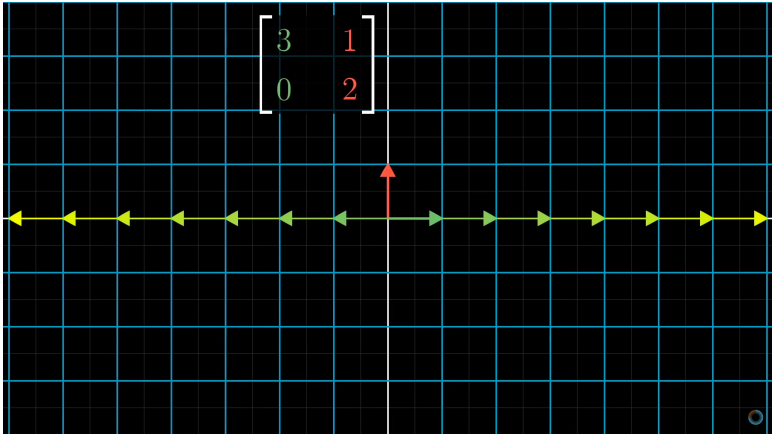


Figure: This happens to all vectors with the same (reverse) direction as the green vector (*source: Youtube of 3Blue1Brown*)

## Transformation of basis vectors (10)

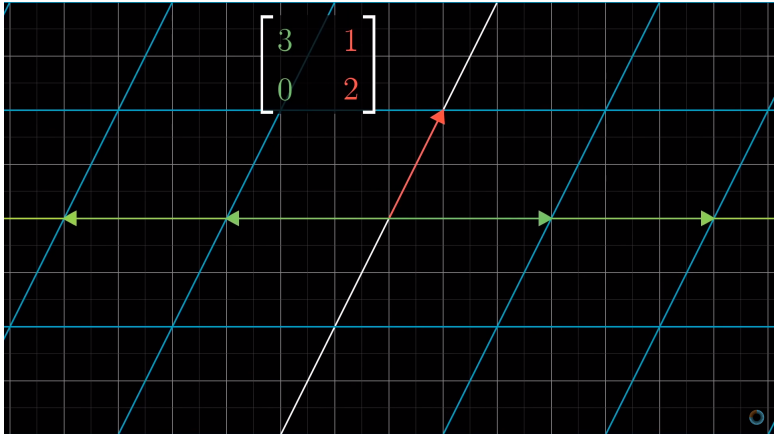


Figure: They are all stretched to 3 times the original vector (*source: Youtube of 3Blue1Brown*)

## Transformation of basis vectors (11)

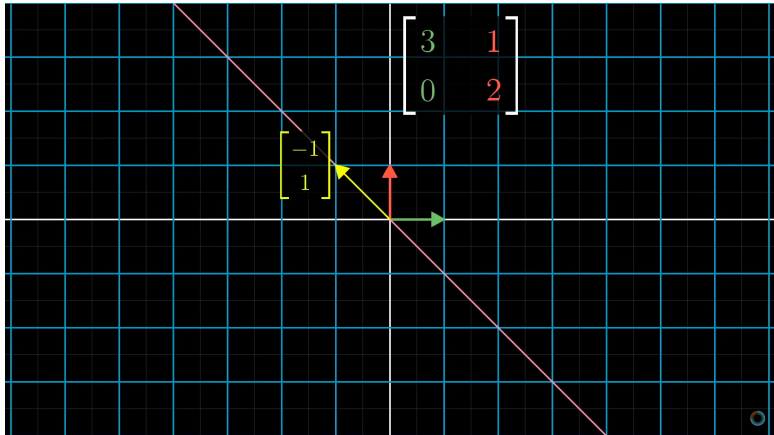


Figure: Another vector with similar property (*source: Youtube of 3Blue1Brown*)



## Transformation of basis vectors (12)

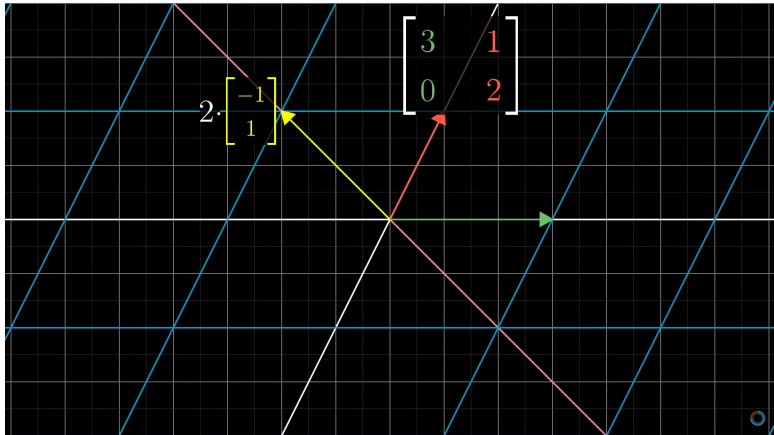


Figure: This vector remains in its position after transformation (*source: Youtube of 3Blue1Brown*)

## Transformation of basis vectors (13)

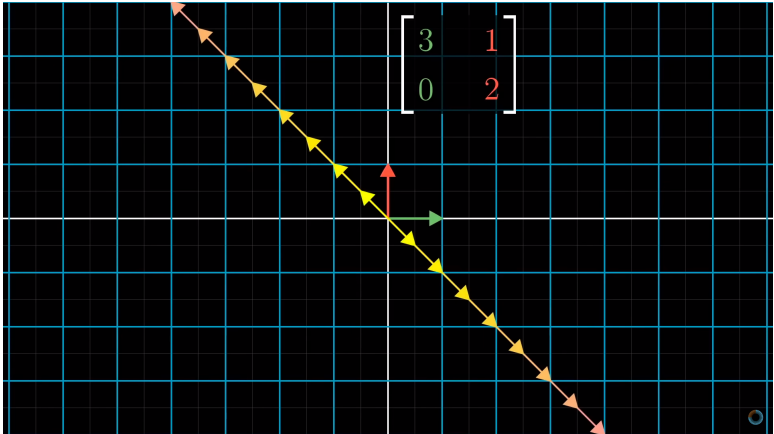


Figure: The property holds for all vectors in the span of its vector  
(source: Youtube of 3Blue1Brown)

# Eigenvectors (1)

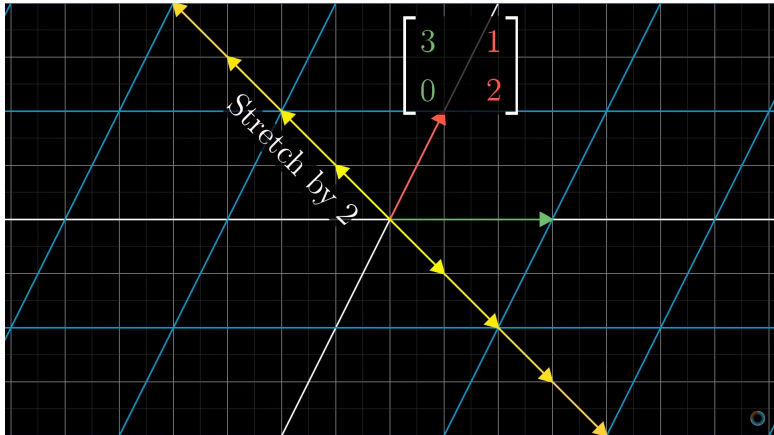


Figure: The yellow vector is stretched by 2 (source: Youtube of 3Blue1Brown)

## Eigenvectors (2)

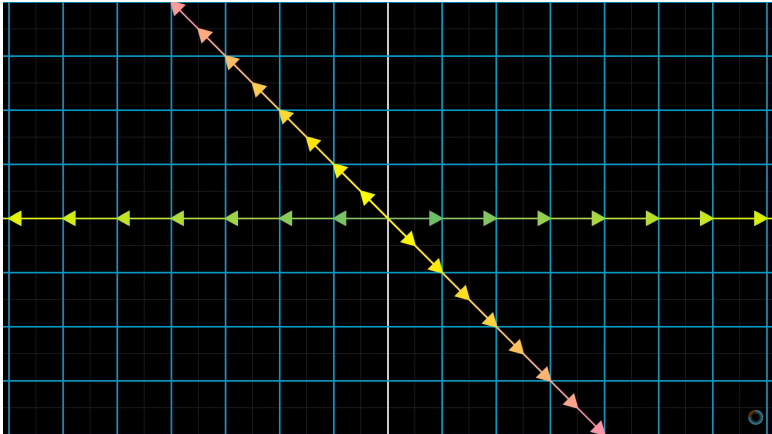


Figure: The green vector is stretched by 3 (source: Youtube of 3Blue1Brown)

## Eigenvectors (3)

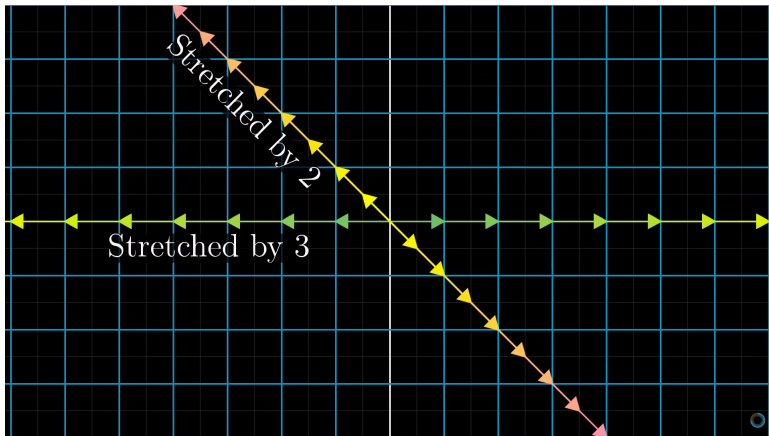


Figure: Source: Youtube of 3Blue1Brown

## Eigenvectors (4)

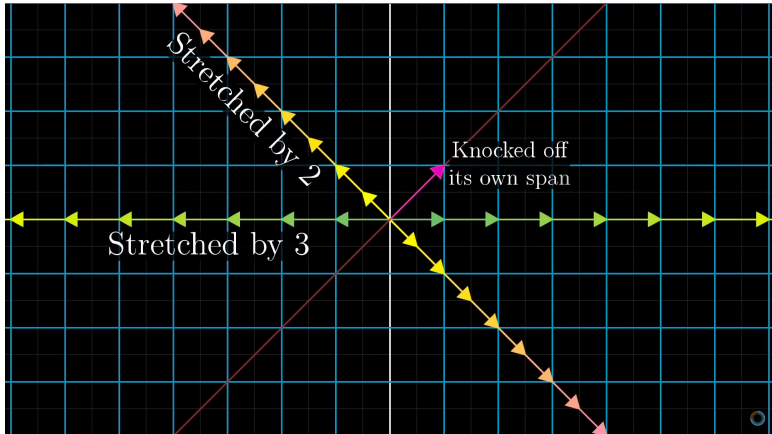
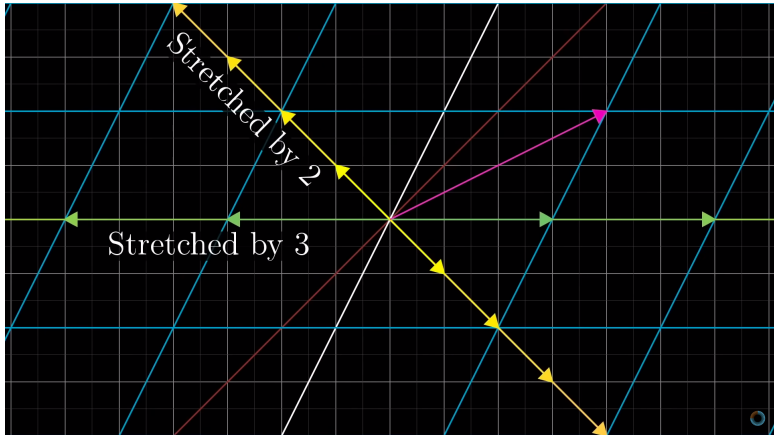


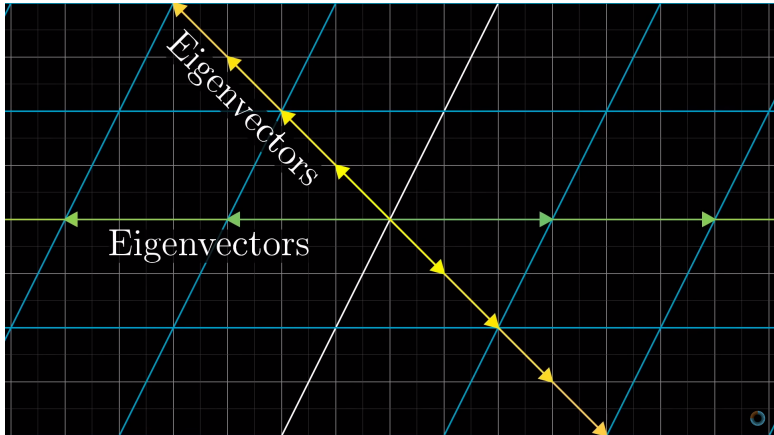
Figure: Other vectors do not stay in their span Source: Youtube of 3Blue1Brown

## Eigenvectors (5)



**Figure:** The transformation keeps the two vectors (yellow and green) in their position (*source: Youtube of 3Blue1Brown*)

## Eigenvectors (6)



**Figure:** The transformation keeps the two vectors in their position  
(source: Youtube of 3Blue1Brown)



## Eigenvectors (7)

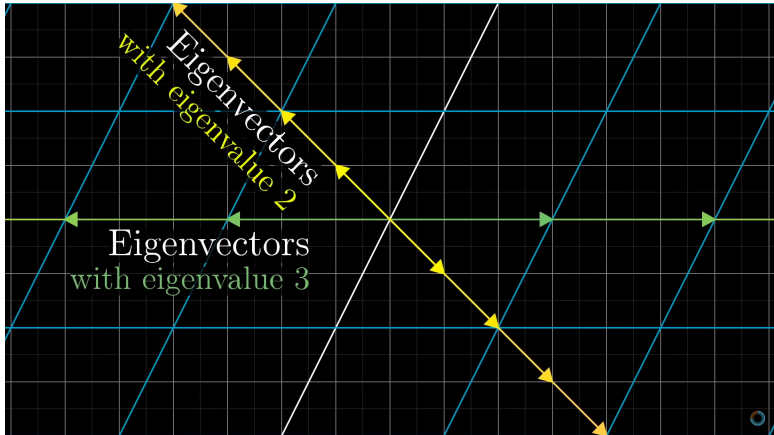


Figure: They are called **eigenvectors** (The transformation keeps the two vectors in their position *source: Youtube of 3Blue1Brown*)

## Eigenvectors (8)

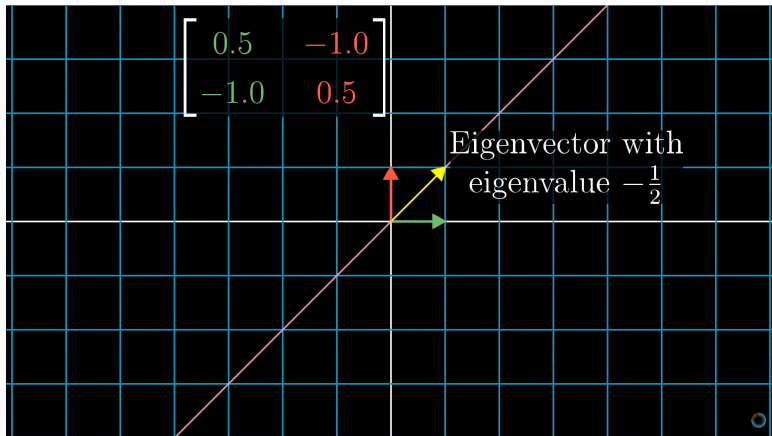


Figure: Prerequisites (source: Youtube of 3Blue1Brown)

# Eigenvectors (9)

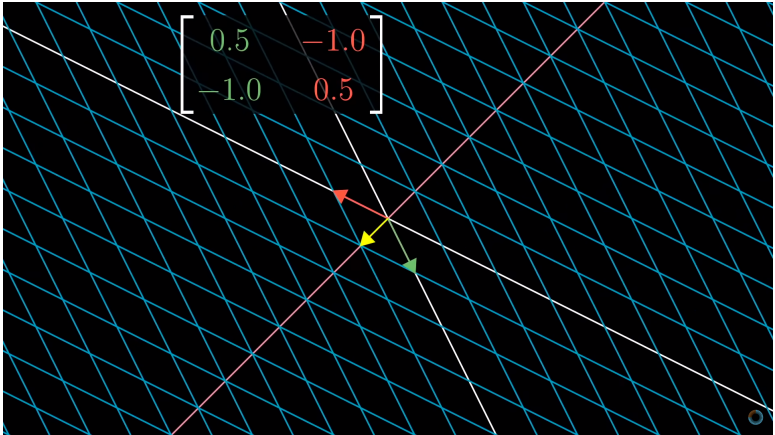


Figure: Prerequisites (source: Youtube of 3Blue1Brown)